

**Appendix to  
“Recessions and the Trend in the US Unemployment Rate” 2021. Kurt G.  
Lunsford. Federal Reserve Bank of Cleveland, *Economic Commentary*, 2021-01**

In this appendix, I describe how I compute both unconditional and conditional forecasts. Let  $u_t$  denote the unemployment rate and  $x_t$  denote the recession indicator. I use a VAR model with these two variables and six lags to compute the forecasts. The VAR model is

$$\begin{bmatrix} x_t \\ u_t \end{bmatrix} = \Gamma_0 + \Gamma_1 \begin{bmatrix} x_{t-1} \\ u_{t-1} \end{bmatrix} + \dots + \Gamma_6 \begin{bmatrix} x_{t-6} \\ u_{t-6} \end{bmatrix} + \begin{bmatrix} e_{x,t} \\ e_{u,t} \end{bmatrix}, \quad (\text{A.1})$$

where  $e_{x,t}$  and  $e_{u,t}$  are the VAR innovations. In the VAR model,  $\Gamma_0$  is a  $2 \times 1$  matrix and  $\Gamma_1, \dots, \Gamma_6$  are each  $2 \times 2$  matrices. The matrices  $\Gamma_0, \Gamma_1, \dots, \Gamma_6$  contain the parameters of the VAR model. I assume that the VAR innovations have the following properties

$$E \left( \begin{bmatrix} e_{x,t} \\ e_{u,t} \end{bmatrix} \right) = 0_{2 \times 1}, \quad (\text{A.2})$$

$$E \left( \begin{bmatrix} e_{x,t} \\ e_{u,t} \end{bmatrix} \begin{bmatrix} e_{x,t} & e_{u,t} \end{bmatrix} \right) = \begin{bmatrix} \sigma_{e,x}^2 & \sigma_{e,ux} \\ \sigma_{e,ux} & \sigma_{e,u}^2 \end{bmatrix}, \quad (\text{A.3})$$

and

$$E \left( \begin{bmatrix} e_{x,t} \\ e_{u,t} \end{bmatrix} \begin{bmatrix} e_{x,t-i} & e_{u,t-i} \end{bmatrix} \right) = 0_{2 \times 2} \text{ for } i \neq 0, \quad (\text{A.4})$$

where  $0_{m \times n}$  denotes an  $m \times n$  matrix of zeros.

I use  $\{u_{-5}, u_{-4}, u_{-3}, u_{-2}, u_{-1}, u_0, u_1, \dots, u_T\}$  to denote the sample of unemployment rate values so that there are a total of  $T + 6$  observations. Similarly, the sample for the recession indicator is  $\{x_{-5}, x_{-4}, x_{-3}, x_{-2}, x_{-1}, x_0, x_1, \dots, x_T\}$ . I use these data samples to estimate  $\Gamma_0, \Gamma_1, \dots, \Gamma_6$  with least squares, and I denote the estimates with  $\hat{\Gamma}_0, \hat{\Gamma}_1, \dots, \hat{\Gamma}_6$ . Then, I estimate the VAR residuals with

$$\begin{bmatrix} \hat{e}_{x,t} \\ \hat{e}_{u,t} \end{bmatrix} = \begin{bmatrix} x_t \\ u_t \end{bmatrix} - \hat{\Gamma}_0 - \hat{\Gamma}_1 \begin{bmatrix} x_{t-1} \\ u_{t-1} \end{bmatrix} - \dots - \hat{\Gamma}_6 \begin{bmatrix} x_{t-6} \\ u_{t-6} \end{bmatrix}. \quad (\text{A.5})$$

I estimate the parameters in (A.3) with

$$\hat{\sigma}_{e,x}^2 = T^{-1} \sum_{t=1}^T \hat{e}_{x,t}^2, \quad \hat{\sigma}_{e,u}^2 = T^{-1} \sum_{t=1}^T \hat{e}_{u,t}^2, \quad \hat{\sigma}_{e,ux} = T^{-1} \sum_{t=1}^T \hat{e}_{u,t} \hat{e}_{x,t}. \quad (\text{A.6})$$

For the purposes of forecasting, I define the following matrices

$$A_0 = \begin{bmatrix} \Gamma_0 \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \end{bmatrix}, \quad A_1 = \begin{bmatrix} \Gamma_1 & \Gamma_2 & \Gamma_3 & \Gamma_4 & \Gamma_5 & \Gamma_6 \\ I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} \end{bmatrix}, \quad J = \begin{bmatrix} I_{2 \times 2} \\ 0_{2 \times 2} \\ 0_{2 \times 2} \\ 0_{2 \times 2} \\ 0_{2 \times 2} \\ 0_{2 \times 2} \end{bmatrix}, \quad (\text{A.7})$$

where  $I_{n \times n}$  is an  $n \times n$  identity matrix. In addition, I use the notation  $z_t = [x_t \quad u_t]'$ . With these matrices and this notation, the VAR model in Equation (A.1) implies

$$\begin{bmatrix} x_{T+h} \\ u_{T+h} \end{bmatrix} = J' \left( \sum_{j=1}^h A_1^{j-1} \right) A_0 + J' A_1^h \begin{bmatrix} z_T \\ z_{T-1} \\ z_{T-2} \\ z_{T-3} \\ z_{T-4} \\ z_{T-5} \end{bmatrix} + J' \sum_{j=1}^h A_1^{h-j} J \begin{bmatrix} e_{x,T+j} \\ e_{u,T+j} \end{bmatrix}. \quad (\text{A.8})$$

Based on Equation (A.8), I can compute the  $h$ -step-ahead *unconditional* forecasts with

$$\begin{bmatrix} \hat{x}_{T+h|T} \\ \hat{u}_{T+h|T} \end{bmatrix} = J' \left( \sum_{j=1}^h \hat{A}_1^{j-1} \right) \hat{A}_0 + J' \hat{A}_1^h \begin{bmatrix} z_T \\ z_{T-1} \\ z_{T-2} \\ z_{T-3} \\ z_{T-4} \\ z_{T-5} \end{bmatrix}, \quad (\text{A.9})$$

where

$$\hat{A}_0 = \begin{bmatrix} \hat{\Gamma}_0 \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \\ 0_{2 \times 1} \end{bmatrix}, \quad \hat{A}_1 = \begin{bmatrix} \hat{\Gamma}_1 & \hat{\Gamma}_2 & \hat{\Gamma}_3 & \hat{\Gamma}_4 & \hat{\Gamma}_5 & \hat{\Gamma}_6 \\ I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} \\ 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & 0_{2 \times 2} & I_{2 \times 2} & 0_{2 \times 2} \end{bmatrix}. \quad (\text{A.10})$$

In equation (A.9), the values of  $z_T, z_{T-1}, z_{T-2}, z_{T-3}, z_{T-4}$ , and  $z_{T-5}$  are the initial conditions or starting points that I use to compute the forecasts.

Next, I want to compute *conditional* forecasts of  $u_t$ , denoted with  $\{\hat{u}_{T+1|T}^c, \dots, \hat{u}_{T+h|T}^c\}$ . I condition these forecasts on a future path of  $x_t$ , denoted with  $\{x_{T+1}^c, \dots, x_{T+h}^c\}$ . In the *Commentary*, I use  $x_{T+j}^c = 0$  for  $j = 1, \dots, h$  where  $h = 240$ . I follow Doan, Litterman, and Sims (1983) to produce these conditional forecasts. I decompose the VAR innovations into a 2-dimensional process  $\epsilon_t = [\epsilon_{1,t} \quad \epsilon_{2,t}]'$ , in which  $\epsilon_{1,t}$  and  $\epsilon_{2,t}$  are uncorrelated, with

$$\begin{bmatrix} e_{x,t} \\ e_{u,t} \end{bmatrix} = \begin{bmatrix} \sigma_{e,x} & 0 \\ \frac{\sigma_{e,ux}}{\sigma_{e,x}} & \sqrt{\sigma_{e,u}^2 - \frac{\sigma_{e,ux}^2}{\sigma_{e,x}^2}} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \end{bmatrix}. \quad (\text{A.11})$$

Macroeconomic researchers sometimes interpret  $\epsilon_t$  as structural or economically interpretable shocks. For example, Waggoner and Zha (1999) refer to  $\epsilon_t$  as a vector of structural shocks. I am not using that interpretation here. Rather, I view  $\epsilon_{1,t}$  or  $\epsilon_{2,t}$  as alternative reduced-form innovations that will be convenient for conditional forecasting.

To see this interpretation more clearly, note that the first row of (A.11) implies that  $\epsilon_{1,t} = \sigma_{e,x}^{-1} e_{x,t}$ . Then, this equation and the second row of (A.11) implies  $e_{u,t} = \frac{\sigma_{e,ux}}{\sigma_{e,x}} e_{x,t} + \sqrt{\sigma_{e,u}^2 - \frac{\sigma_{e,ux}^2}{\sigma_{e,x}^2}} \epsilon_{2,t}$ , noting that  $e_{x,t}$  and  $\epsilon_{2,t}$  are uncorrelated. Then, the decomposition is akin to projecting or regressing  $e_{u,t}$  on  $e_{x,t}$  and having  $\sqrt{\sigma_{e,u}^2 - \frac{\sigma_{e,ux}^2}{\sigma_{e,x}^2}} \epsilon_{2,t}$  be the residual that affects  $e_{u,t}$  but not  $e_{x,t}$ . Hence, I view (A.11) as simply a way to orthogonalize the reduced-form innovations with linear projections – not as a way to uncover structural shocks. To ease notation, I use

$$L = \begin{bmatrix} \sigma_{e,x} & 0 \\ \frac{\sigma_{e,ux}}{\sigma_{e,x}} & \sqrt{\sigma_{e,u}^2 - \frac{\sigma_{e,ux}^2}{\sigma_{e,x}^2}} \end{bmatrix} \quad (\text{A.12})$$

so that  $[e_{x,t} \ e_{u,t}]' = [\epsilon_{1,t} \ \epsilon_{2,t}]' L'$ .

I produce the conditional forecasts by choosing a collection of future shocks, denoted with  $[\epsilon_{1,T+1|T}^c \ \epsilon_{2,T+1|T}^c \ \dots \ \epsilon_{1,T+h|T}^c \ \epsilon_{2,T+h|T}^c]$ , such that  $x_{T+1} = x_{T+1}^c$ ,  $x_{T+2} = x_{T+2}^c$ , ...,  $x_{T+h} = x_{T+h}^c$ . I define  $\hat{X} = [\hat{x}_{T+1|T}, \dots, \hat{x}_{T+h|T}]'$  and  $X^c = [x_{T+1}^c, \dots, x_{T+h}^c]'$  to be  $h \times 1$  vectors of unconditional and conditional forecasts. Then using (A.8), (A.9), (A.10), (A.11), and (A.12), I write the constraints,  $x_{T+1} = x_{T+1}^c$ ,  $x_{T+2} = x_{T+2}^c$ , ...,  $x_{T+h} = x_{T+h}^c$ , as

$$X^c - \hat{X} = M \begin{bmatrix} \epsilon_{1,T+1|T}^c \\ \epsilon_{2,T+1|T}^c \\ \vdots \\ \epsilon_{1,T+h|T}^c \\ \epsilon_{2,T+h|T}^c \end{bmatrix}, \quad (\text{A.13})$$

in which  $M$  is an  $h \times 2h$  matrix given by

$$M = \begin{bmatrix} [1 \ 0_{1 \times 11}]JL & 0_{1 \times 2} & \dots & 0_{1 \times 2} \\ [1 \ 0_{1 \times 11}]A_1JL & [1 \ 0_{1 \times 11}]JL & \dots & 0_{1 \times 2} \\ \vdots & \vdots & \ddots & 0_{1 \times 2} \\ [1 \ 0_{1 \times 11}]A_1^{h-1}JL & [1 \ 0_{1 \times 11}]A_1^{h-2}JL & \dots & [1 \ 0_{1 \times 11}]JL \end{bmatrix}. \quad (\text{A.14})$$

Then, I estimate the values of  $[\hat{\epsilon}_{1,T+1|T}^c \quad \hat{\epsilon}_{2,T+1|T}^c \quad \dots \quad \hat{\epsilon}_{1,T+h|T}^c \quad \hat{\epsilon}_{2,T+h|T}^c]$  by minimizing

$$(\hat{\epsilon}_{1,T+1|T}^c)^2 + (\hat{\epsilon}_{2,T+1|T}^c)^2 + \dots + (\hat{\epsilon}_{1,T+h|T}^c)^2 + (\hat{\epsilon}_{2,T+h|T}^c)^2 \quad (\text{A.15})$$

subject to (A.13). This minimization yields

$$\begin{bmatrix} \hat{\epsilon}_{1,T+1|T}^c \\ \hat{\epsilon}_{2,T+1|T}^c \\ \vdots \\ \hat{\epsilon}_{1,T+h|T}^c \\ \hat{\epsilon}_{2,T+h|T}^c \end{bmatrix} = \hat{M}' (\hat{M} \hat{M}')^{-1} (X^c - \hat{X}), \quad (\text{A.16})$$

in which  $\hat{M}$  takes the same form and  $M$ , but with  $\hat{A}_1$  in place of  $A_1$  and

$$\hat{L} = \begin{bmatrix} \hat{\sigma}_{e,x} & 0 \\ \hat{\sigma}_{e,ux} & \sqrt{\hat{\sigma}_{e,u}^2 - \frac{\hat{\sigma}_{e,ux}^2}{\hat{\sigma}_{e,x}^2}} \\ \hat{\sigma}_{e,x} & \end{bmatrix}$$

in place of  $L$ . I then feed  $[\hat{\epsilon}_{1,T+1|T}^c \quad \hat{\epsilon}_{2,T+1|T}^c \quad \dots \quad \hat{\epsilon}_{1,T+h|T}^c \quad \hat{\epsilon}_{2,T+h|T}^c]$  into (A.8) using the estimates in (A.10) to compute the conditional unemployment rate forecasts,  $\{\hat{u}_{T+1|T}^c, \dots, \hat{u}_{T+h|T}^c\}$ .

## References

Doan, Thomas, Robert Litterman, and Christopher A. Sims. 1983. "Forecasting and Conditional Projection Using Realistic Prior Distributions." NBER Working Paper, No. 1202. DOI: [10.3386/w1202](https://doi.org/10.3386/w1202).

Waggoner, Daniel F., and Tao Zha. 1999. "Conditional Forecasts in Dynamic Multivariate Models." *Review of Economics and Statistics*, 81(4): 639-651. DOI: [10.1162/003465399558508](https://doi.org/10.1162/003465399558508).